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Total Number of Pages: 02

**B.Tech**  
**PEME5407**

**8<sup>th</sup> Semester Regular / Back Examination 2016-17**

**MECHATRONICS**

**BRANCH(S): CSE, IT, ITE**

**Time: 3 Hours**

**Max Marks: 70**

**Q.CODE: Z404**

**Answer Question No.1 which is compulsory and any five from the rest.  
The figures in the right hand margin indicate marks.**

- Q1 Answer the following questions: (2 x 10)**
- a) What is meant by the term “Real time mechatronics system”?
  - b) State any two differences between micro switch and reed switch.
  - c) What do you understand by memory mapping?
  - d) Domestic washing machine is a mechatronic approach – Justify.
  - e) Define power rating of a potentiometer.
  - f) What is latching in PLC’S?
  - g) How a traditional design of pressure control in a large tank is improved by mechatronic design?
  - h) What are the steps involved in the operation of a digital controller?
  - i) What is Shift register? What is the data required for a shift register?
  - j) How does a microcontroller differ from a microprocessor?
- Q2 a) Explain the principle of operation of inductive proximity sensor with a neat diagram. (5)**
- b) With an aid of a neat sketch, describe the working of an absolute encoder. (5)**
- Q3 a) Explain the various stages in mechatronics design approach and state how it differs from the traditional approach. (5)**
- b) With a neat diagram, describe the working of a Directional control valves. (5)**
- Q4 With the help of a proper control circuits explain the speed control of AC and DC motors. (10)**
- Q5 a) Explain the configuration of PLC. List the considerations in selecting a PLC. (5)**
- b) With a suitable graph, discuss the specifications and characteristics of a stepper motor. (5)**

- Q6** a) A potentiometer which is used to measure the rotational position of the shaft has 850 Turns of wire. The input range is from  $-160^\circ$  to  $+160^\circ$ . The output range is from 0 V to 12 V. Determine (i) The span (ii) Sensitivity (iii) Average resolution in volts. **(5)**
- b) Explain about the hydraulic and pneumatic actuation systems used in automation. **(5)**
- Q7** a) Explain the working of PID controller with a neat sketch. **(5)**
- b) Investigate the analog-to-digital converters used in mechanical measuring systems. Find the sampling rate, the quantization bits, and the technique used for the conversion. **(5)**
- Q8** **Write short notes on any two:** **(5 x 2)**
- a) Multiplexers
  - b) Rotary actuators
  - c) Fluid system building blocks
  - d) Adaptive control